Developers meeting at ESRF November 2018

Developers meeting in Grenoble (ESRF) between 2018-11-15 and 2018-11-16.

Present: Martin Savko (MS), Mikel Eguiraun (ME), Ivars Karpics (IK), Michael Hellmig (MH), Jan Meyer (JM), Rasmus Fogh (RF), Jakob Urbschat (JU), Bixente Rey (BR), Antonia Beteva (AB), Marcus Oskarsson (MO).

No participants absent

The aim of the meeting was to:

- Merge HardwareRepository (HR) 2.2 and current master to create a basis (3.0-alpha) for what will later become HR version 3.0.
- To identify Hardware Objects and other parts of HR that should be refactored as part of the merge process.
- Discuss and establish coding standard and routines to be used for version 3.0 of HR.
- Outline a roadmap for the release of HR 3.0 that can be given to the steering committee in February

A document with a few preparatory assignments designed to indicate where one could expect to find the biggest differences between the two branches 2.2 and master was circulated before the meeting. The document further requested all sites to create PR's with all changes to be included in the merge.

"The **absolutely most important** step would be for each site to make a PR with their local changes before we perform the merge. It will further be **very complicated to add features** to either 2.2 or 2.3 (master before the merge) while we are in the process of creating 3.0 (merging 2.2 into 2.3 with following cleanup)"

The complete document can be found in appendix

Day 1 (2018-11-15)

Meeting opened 9:28 by (MO), there were no additions to the already circulated agenda. The meeting agenda can be found in appendix.

There were two pull requests, #251 and #234, still remaining before the 2.3 branch could be created from the master branch. PR #234 was merged directly. PR #251 by RH required some discussion mainly because the already existing method *getHardwareRepositoryPath()* was removed and replaced by a semantically different method *findInRepository(name)*. The former returning a directory and the later a file. Both AB and BR argued that the *getHardwareRepositoryPath()* should not be removed. It was decided to in anyways merge PR #251 since the method *getHardwareRepositoryPath()* currently was unused. However it was said that *findInRepository(name)* should be looked at further during the work with HR 3.0.

Branch 2.3 was created from master (commit 9496e78f...) and merging HR 2.2 into master started 9:48. The merge proceeded smoothly the biggest amount of conflicts were in queue_model_objects_v1.py, queue_entry.py, ISPyBClient2.py and Cats90.py. The method *getHardwareRepositoryPath()* that was removed by PR #251 was added back again. The merge finished at 16:19.

MO and AB presented the currently used coding conventions and tools as well as some ideas to be used as a discussion starter. The ideas presented was for improving the process for the work of HR 3.0 and included

- Clarify meaning of abstract and generic HO's
- Improving folder structure
- A way to enforce PEP-8 coding convention
- Writing tests and setting up CI
- Improving code documentation

The topic *"Clarify meaning of abstract and generic HO's"* required further discussion to explore the issue. There was otherwise a generally positive view of the ideas presented. It was decided to continue the discussion on these points at a later stage of the meeting.

AB continued to present a draft merge of MiniDiff and GenericDiffractometer to be used as a basis for discussion of the functional merge of a new common diffractometer object. It was decided that AB will continue the work on the draft merge and present a PR what will be discussed at a future developers meeting.

Day 1 ends at 18:30

Day 2 (2018-11-16)

The improvement suggestions on code convention and tools are discussed further and its decided

- To stop using the Generic prefix from HO's since it is often misunderstood and confused with Abstract. The Abstract prefix is to be used in all cases where one wants define a common API for a HO for example AbstractDiffractometer. The need for having a intermediate level of abstraction prefixed with Base is discussed along with if Abstract classes are allowed to have a certain level of implementation.
- To cleanup the Hardware Object directory structure; creating a mockup folder, moving the contents of detectors to the root folder and moving all concrete sample changer implementations to the root folder. As well as renaming the modules modules queue_model_objects_v1 to queue_model_objects and ISPyBClient2 to ISPyBClient
- To use PEP-8 for at least all new code and investigate ways of automatically converting the current code base to PEP-8 using tools like autopep8 or Black.
- To write Python3 compatible code
- To further explore means of implementing tests and continuous integration (CI)
- To use semantic versioning according to semver.org:

"Given a version number MAJOR.MINOR.PATCH, increment the:

- MAJOR version when you make incompatible API changes,
- MINOR version when you add functionality in a backwards-compatible manner, and
- $\circ~$ PATCH version when you make backwards-compatible bug fixes."

MS took the initiative to try autopep8 and Black on the existing code base, the preliminary result looks promising. MS and AB expressed the wish to further look into the problem of converting the existing code base to PEP-8

AB presents some ideas and a draft merge of the AbstractCollect and AbstractMultiCollect that can be used as basis for discussion. Her proposal to introduce the concept of 'phases to collection, possibly in the form of 'pre-execute' and 'execute' commands was well received, as was her proposal to standardise access to motor objects to using a fixed set of role names. Both MO and AB expresses that it would be beneficial with an object for accessing "beamline wide" functionality to avoid duplication of logic. Such functionality could for instance be opening and closing shutters, reading certain values and accessing lims. This functionality is today often accessed via the collect object itself which often adds an

unnecessary level of logic. MO also expresses that it would be good if the collect parameters could be passed as a well defined "Data Object" preferably immutable instead of a python dictionary. It's agreed that the draft collect presented by AB is to be continued and further discussed during a coming developers web meeting.

Other HO's and parts of the HR to improve are identified; there is an overall wish to improve Session and especially the path related functions. There is also wishes to improve the queue related functions and IK expresses that he has some ideas that he could present during a developers web meeting.

The contents of the road map requested by the steering committee is discussed. There was general consensus that it should be possible have a 3.0.0-alpha version that runs on mockups by the next MXCuBE meeting in Lund. The exact contents of 3.0.0-alpha remains to be decided.

Day 2 ends 15:00

Summary

Actions:

- Branch 2.3 created from master (9496e78f...)
- Merged branches 2.2 and master, 2.2 into master

Work to be done/discussed before/during the next developers web meeting:

- AB to continue work on AbstractDiffractometer to create a PR that can be further discussed during a developers web meeting.
- To continue the work on the merged version of AbstractCollect and AbstractMultiCollect to be discussed during the next developers meeting.
- Session, Queue related objects, an object for "beamline wide" functions and "Pure data class"
- Converting current code base to PEP-8, status report by MS and/or AB
- Decide on roadmap and contents of 3.0.0-alpha

Decisions

• To stop using the Generic prefix from HO's since it is often misunderstood and confused with Abstract. The Abstract prefix is to be used in all cases where one wants define a common API for a HO for example AbstractDiffractometer.

- To cleanup the Hardware Object directory structure; creating a mockup folder, moving the contents of detectors to the root folder and moving all concrete sample changer implementations to the root folder
- Rename modules: queue_model_objects_v1 to queue_model_objects and ISPyBClient2 to ISPyBClient
- To use PEP-8 compatible code for at least all new code and investigate ways of automatically converting the current code base to PEP-8 using tools like autopep8 or Black.
- To write Python3 compatible code
- To further explore means of implementing tests and continuous integration (CI)
- To use semantic versioning according to semver.org: *"Given a version number MAJOR.MINOR.PATCH, increment the:*
 - MAJOR version when you make incompatible API changes,
 - *MINOR version when you add functionality in a backwards-compatible manner*
 - PATCH version when you make backwards-compatible bug fixes."

Appendix - Meeting agenda

Day 1: 9h-12:30h

- 09.00: Meet in ESRF mezzanine
- Perform merge
 - Create branch 2.3 from master
 - Merge master into 2.2 to create new master that will become version 3.0

Day 1: 14h-18h

- Functional merge
 - Diffractometer HardwareObjects, based on GenericDiffractometer (master) and MiniDiff (2.2)
 - Collect HardwareObject, based on AbstractCollect (master & 2.2) and AbstractMulticollect (2.2)

Day 1: 19h -

• Dinner downtown for those who wants

Day 2: 9h-12h

- (Continue with tasks from previous day, if left)
- Identify HardwareObjects to continue with for instance: Attenuators, Energy and Resolution
- Tasks to be done until next web meeting
- (Test with Mockups, if time is given)

Day 2: 13h-15h

- Discuss and clarify the points/tasks needed to be done for the roadmap that the steering committee expects in February
- (Brief discussion on coding standard and routines to be used for version 3)

Appendix - Meeting "Homework" document

Homework

Its necessary for each site to get in depth knowledge of what's used on their beamlines and what will be important to consider during the merge. The **absolutely most important** step would be for each site to make a PR with their localchanges before we perform the merge. It will further be **very complicated to add features** to either 2.2 or 2.3 (master before the merge) while we are in the process of creating 3.0 (merging 2.2 into 2.3 with following cleanup)

Please complete the following steps before the meeting:

Task \ site	ALBA	BESSY	DESY	ELETTRA	EMBL	ESRF	GPhL	MAXIV	SOLEIL
Running mockup version of qt/web									
Update example xmls									
List all used hwobj classes (table on page 3)									
Submit changes to master/2.2									

We will further take a closer look at the Collect routines and Diffractometer HardwareObjects, so please compare those in order to get an idea what the principal differences are and what is important to you, doing for instance the following:

- 1. Compare AbstractMultiCollect on 2.2 with AbstarctCollect on master: # Compare AbstractMultiCollect on 2.2 with AbstractCollect on master: git diff 2.2:HardwareObjects/AbstractMultiCollect.py master:HardwareObjects/AbstractCollect.py
- 2. MiniDiff.py on 2.2 with GenericDiffractometer on master # Compare AbstractMultiCollect on 2.2 with AbstarctCollect on master: git diff 2.2:HardwareObjects/MiniDiff.py master:HardwareObjects/GenericDiffractometer.py

It's also **strongly recommended** to perform the merge command just to get an overview where the most evident conflicts

are located and how these could affect you:

git checkout 2.2; git merge master; git gui

Do not forget to fill out the table on the following page !

List of used classes:

ALBA	BES SY	DESY 2)	EMBL	ELETTRA 3)	ESRF	GPhL 1)	ΜΑΧΙν	SOLEIL
AbstractCollect AbstractDataA nalysis AbstractDetect or AbstractMotor		AbstractMotor AbstractAperture AbstractCollect AbstractDataAnal ysis AbstractEnergy AbstractEnergyS can AbstractFlux AbstractFlux AbstractMultiColl ect AbstractSlits AbstractXRFSpe ctrum	AbstractApert ure AbstractAtten uators AbstractColle ct AbstractDete ctor AbstractEner gyScan AbstractMoto r AbstractSlits AbstractXRF Spectrum	AbstractMulti Collect AbstractData Analysis	AbstarctMulti Collect AbstractEner gyScan AbstractMCA AbstractMotor	AbstractApert ure AbstractColle ct AbstractData Analysis AbstractDetec tor AbstractEnerg y AbstractEnerg yScan AbstractFlux AbstractFlux AbstractSlits AbstractXRFS pectrum	AbstractColl ect AbstractMoto r	AbstractMotor AbstractCollect AbstractXRFSp ectrum AbstractEnergy Scan AbstractDetecto r AbstractApertur e
GenericVideo Device GenericDiffract ometer SampleChang er		GenericDiffracto meter GenericParallelP rocessing GenericVideoDe vice	GenericDiffra ctometer GenericParall elProcessing GenericSamp leChanger GenericVideo Device	GenericSam pleChanger GenericDiffra ctometer	GenericSamp leChanger	GenericDiffrac tometer GenericVideo Device GenericSampl eChanger	GenericDiffra ctometer GenericSam pleChanger	GenericDiffracto meter GenericSample Changer GenericVideoD evice
BeamlineSetu p DataAnalysis ISPyBClient2 InstanceServer Session QueueManage r QueueModel Qt4_TangoLim aVideo Qt4_Graphics Manager Cats90 CatsMaint ParallelProces sing LdapLogin SardanaMotor (sample_centri ng)		CentringMath Energy MotorWPositions Qt4_GraphicsMa nager SardanaMotor ApertureMockup AutoProcessing Mockup BeamInfoMockup BeamlineSetup BeamlineTestMo ckup BeamstopMockup CameraMockup CollectEmulator CollectEmulator CollectEmulator CollectMockup DataAnalysis DiffractometerMo ckup EnergyMockup EnergyScanMoc kup FluxMockup GphIWorkflow GphIWorkflowCo nnection InstanceServer	Attenuators BeamlineSet up BeamlineTool s CentringMath DataAnalysis DozorParallel Processing ExporterMoto r ExporterZoo m ISPyBClient2 InstanceServ er MDFastShutt er MiniKappaCo rrection MicrodiffLight Session QueueManag er QueueModel XMLRPCSer ver Qt4_VimbaVi deo Qt4_Graphic	MicrodiffInO ut TangoShutte r MicrodiffBea mstop MicrodiffInO utMockup ShutterMock up BeamlineSet up EnergyScan Mockup DataAnalysis EdnaWorkflo w Shapes PlottingMock up AbstractData Analysis XMLRPCSer ver QueueModel	BeamInfo BeamlineSetu p Bliss BlissActuator BlissInOut BlissMotor BlissWagoCo unter Camera DataAnalysis EdnaWorkflo w Energy FilterAxis Frontend GphIWorkflow GphIWorkflow GphIWorkflow Connection InOut InstanceServ er ISPyBClient2 ISPyBRestCli ent kb Lakeshore LdapLogin LimaVideo MachCurrent	ApertureMock up AttenuatorsM ockup BeamInfoMoc kup BeamlineSetu p BeamlineTest Mockup BeamstopMoc kup CollectMocku p DataAnalysis DetectorMock up DoorInterlock Mockup EnergyMocku p EnergyMocku p EnergyScanM ockup FluxMockup InstanceServe r ISPyBClient2 Mockup MachineInfoM ockup	BeamlineSet up ISPyBClient2 ISPyBRestCl ient QueueMana ger QueueModel Session (inherited) Cats90 CatsMaint SardanaMot or MicrodiffAper ture BeamInfo(in heritted) Energy Resolution DataAnalysis TangoShutte r MicrodiffLigh t MicrodiffInO ut TangoLimaVi	BeamlineSetup ISPyBClient2 LdapLogin InstanceServer Session QueueManager Qt4_GraphicsM anager Qt4_VimbaVide o XMLRPCServer MicrodiffInOut MicrodiffInOut MicrodiffMotor MicrodiffLight Energy Resolution EnergyScanMo ckup XRFSpectrumM ockup DetectorMocku p Shapes Cats90 CatsMaint

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	ISPyBClient2Moc kup LdapLoginMocku p MachineInfoMoc kup MiniKappaCorrec tion MotorMockup MultiCollectMock up ParallelProcessin gMockup QueueManager QueueModel RedisClient ShapeHistory SlitsMockup UnitTest XRFSpectrumMo ckup	sManager		MD2Motor MD3UP Microdiff MicrodiffApert ure MicrodiffBea mstop MicrodiffBea mstopDistanc e MicrodiffFocu sMotor MicrodiffHold erlength MicrodiffLight MicrodiffLight MicrodiffLight Beamstop MicrodiffSam plePseudo MicrodiffZoo m MiniDiff Pilatus QueueManag er QueueModel Resolution sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD sample_chan ger.FlexHCD Maintenance Scintillator Session Shapes TangoLimaVi deo TangoShutter XMLRPCServ er XRFSpectru m	MicrodiffZoom Mockup MotorMockup Diffractometer Mockup CollectMocku p ParallelProce ssing sample_chan ger.PlateMani pulatorMocku p Qt4_Graphics Manager Qt4_VideoMo ckup QueueManag er QueueManag er QueueModel ResolutionMo ckup ShutterMocku p SampleChang erMockup Session SlitsMockup XMLRPCServ er XRFSpectrum Mockup XMLRPCServ er XRFSpectrum Mockup Also the following: CommandCo ntainer Device DeviceContai ner Equipment HardwareObj ect HardwareObj ect Natare Procedure QueueEntryC ontainer	deoDevice MicrodiffZoo m Shapes CentringMat h ControlSyste mChannel	
ALBAAutoProc essing ALBABackLigh t ALBABeamInf o ALBAZoomMo tor ALBACalibrati on	Centring DigitalZoomMoto r MjpgStreamVide o NanoDiff	EMBLApertur e EMBLAutopr ocessing EMBLBeamI nfo EMBLBeamIi neTest EMBLBeamst op	ELETTRA/T angoEnergy ELETTRA/G enericDiffract ometer ELETTRA/T angoChanne I ELETTRA/G alilAxis	BlissHutchTri gger BlissRontecM CA ESRFEnergy Scan ESRFSession ID232BeamC mds ID232BeamD	CollectEmulat or GphlWorkflow Connection GphlWorkflow	BIOMAXEige r BIOMAXTra nsmission MAXIVAutoP rocessing MaxIVSessio n BIOMAXRes olution	SOLEILISPyBCI ient SOLEILSession SOLEILPss SOLEILSafetyS hutter SOLEILMachin eInfo SOLEILLdapLo gin

	-	1				
ALBACatsMai nt ALBACats ALBADataAnal ysis ALBAISPyBCli ent ALBAFastShut ter ALBAFastShut ter ALBAFrontEnd ALBAFrontLig ht ALBAMiniDiff ALBAMiniDiff ALBAMiniDiff ALBACollect ALBAEpsActu ator ALBAPilatus ALBASession ALBASession ALBASupervis or ALBATransmis sion ALBAZoomMo torAutoBrightn ess ALBAZoomMo tor		EMBLDoorInt erlock EMBLEnergy Scan EMBLExport erClient EMBLImageT racking EMBLFlux EMBLMachin eInfo EMBLMINIDIff EMBLCollect EMBLPPUCo ntrol EMBLPPUCo ntrol EMBLPArallel Processing EMBLSafety Shutter EMBLXRFSp ectrum Marvin TINEMotor	ELETTRA/EI ettraBeamInf o ELETTRA/IS PyBClient2M ockup ELETTRA/EI ettraSession ELETTRA/S ampleChang erElettra ELETTRA/M D2TangoMot or ELETTRA/M D2TangoCo axiaIZoom ELETTRA/M D2TangoCo axiaIZoom ELETTRA/M D2TangoCo axiaIZoom ELETTRA/M D2TangoCo axiaIZoom ELETTRA/M D2TangoCo axiaIZoom ELETTRA/M D2Shutter ELETTRA/M D2Shutter ELETTRA/M D2Shutter ELETTRA/M U2Shutter ELETTRA/M D2Shutter ELETTRA/M D2TangoApe rture ELETTRA/M D2TangoApe rture ELETTRA/Z esolutionElet tra ELETTRA/T angoDiffract ometerMD2 ELETTRA/T angoActuato r ELETTRA/T angoActuato r ELETTRA/T angoCryo ELETTRA/T angoCryo ELETTRA/T	efiner ID232BeamIn fo ID232HutchTr igger ID232MultiCo Ilect ID232Photon Flux ID29BeamC mds ID29EnergyS can ID29MultiColl ect ID29PhotonFl ux ID29XRFSpe ctrum ID30A3Photo nFlux ID30BBeamIn fo ID30BABeamIn fo ID30BBeamIn fo ID30BBeamIn fo ID30BBeamIn fo ID30BBeamIn fo ID30BABeamIn	MachInfo BIOMAXApe rture BIOMAXBea mlineActions BIOMAXEne rgy BIOMAXMD 3Camera MAXIVMicro diffInOut	SOLEILUndulat or TangoDCMotor TangoShutter PX1BeamInfo PX1TangoLight PX1Attenuator PX1CatsMaint PX1DetectorDis tance PX1MiniDiff PX1EnergySca n PX1Eiger PX1AutoProces sing PX1Cryotong PX1Resolution SmargonAxis Smargon ChipManager PX1Configurati on TangoDCMotor WPositions TangoDCMotor WPositions TangoMachCurr ent PX2BeamInfo PX2BeamInfo PX2Attenuator PX2Collect PX2Collect PX2Collect PX2Collect PX2Collect PX2Collect PX2Collect PX2Resolution PX22Collect PX22EnergySca n PX22Collect PX22EnergySca
			D2TangoLig htLevel			

- 1) These are all HardwareObjects loaded in a standard mock run, plus their superclasses. That does not mean that they are all *used*. GPhL does not do plates, video, xmlrpc, xrf, energy scan, or beamline test, for instance.
- 2) The same as for GPhL goes for DESY as well. Only the classes in the first paragraph are really doing something, the second paragraph came with the mockup.
- 3) The ELETTRA specific HardwareObjects are not yet in the GitHub repository.