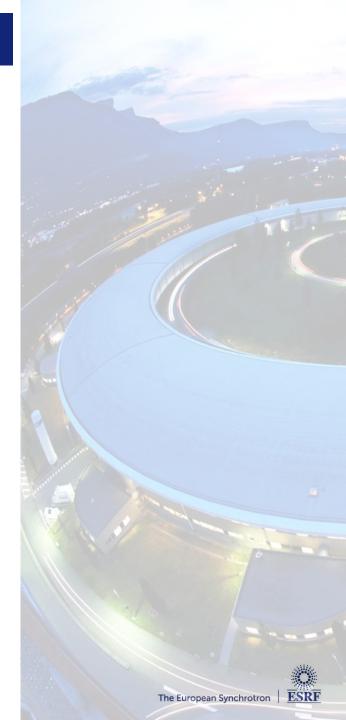


ESRF | The European Synchrotron

Outline

- News from the developers committee
- Feature review
- MXCUBE at ESRF





On behalf of the developers committee

News from the developers committee

 As always monthly meetings - minutes can be found at https://mxcube.github.io/mxcube/doc/developers_meetings/index.html

From last MXCuBE meeting discussions on: Configuration - XML to YAML conversion, web-security and deployment, new queue features, unattended data collections

 Code camp on mxcubecore and mxcubeweb development with an introduction to Javascript and React development - October 2023

Talks and minutes available on:

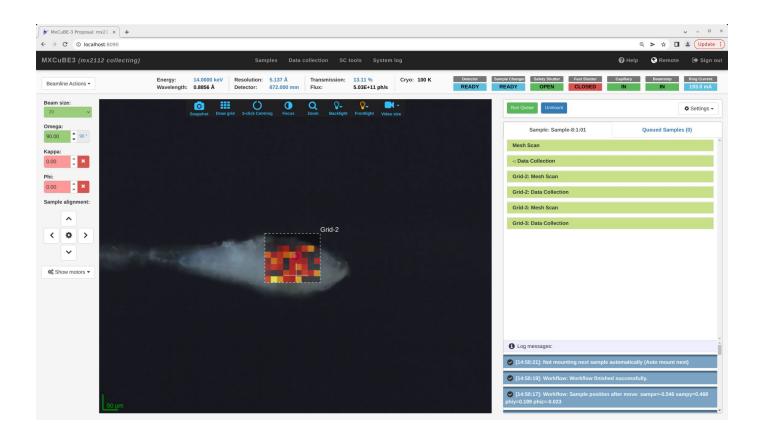
https://mxcube.github.io/mxcube/doc/developers meetings/index.html

Code camp on documentation - March 2024
 Very nice collaborative effort resulting in:

https://mxcubeweb.readthedocs.io https://mxcubecore.readthedocs.io

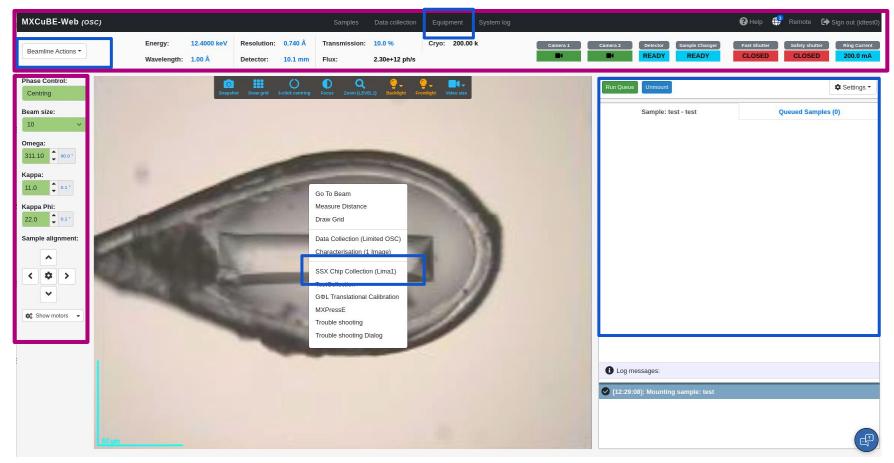
Still in progress and a continuous process!

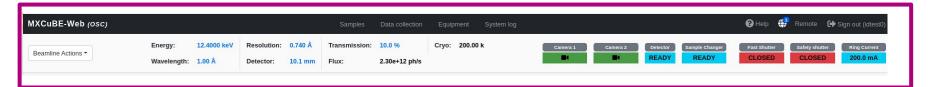




Same principle interface on all sites

To a certain extent configurable instrumentation control, procedures / methods







The display of available instrumentation is configurable in ui.yaml

To the left motor control and on the top "beamline setup"

```
beamline_setup:
id: beamline_setup
components:

label: Beamstop
attribute: beamstop

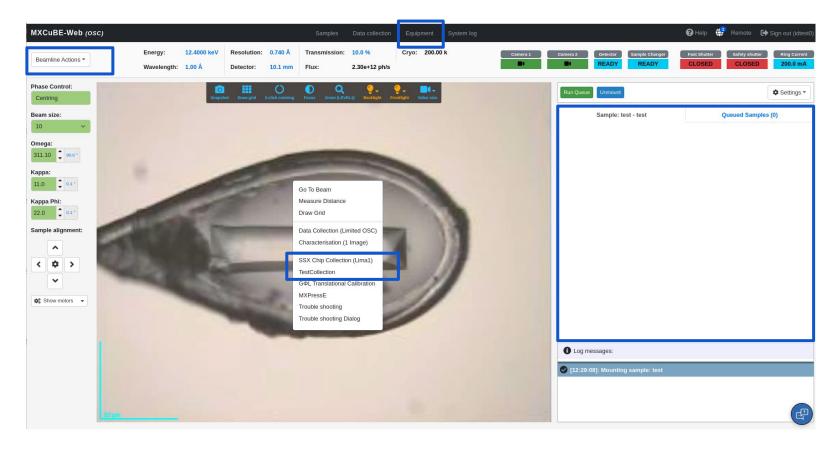
label: Capillary
attribute: capillary

label: Fast Shutter
attribute: fast_shutter

label: Safety shutter
attribute: safety_shutter

label: Detector
attribute: detector

label: Energy
attribute: energy
step: 0.001
precision: 4
suffix: keV
```

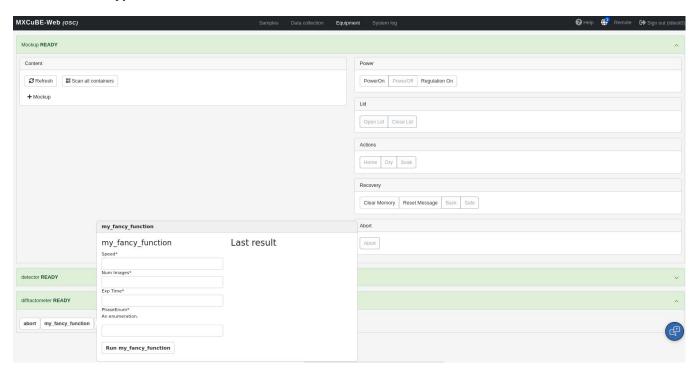


- Equipment view For not so often used or temporary instrumentation commands
- Beamline action For procedures that are frequently used and involves more than a simple command
- Queue entry / task For collecting data



Equipment view - For less often or temporary instrumentation commands

- For convenience, maintenance and workarounds
- Automatic simple test/maintenance UI for type hinted and "exported" (in .xml file)
- Possible via typehints

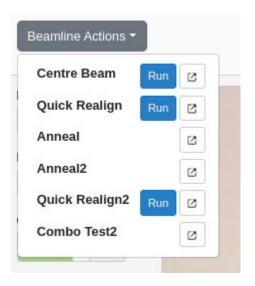


Methods are automatically added if they are "exported" with the export tag and the method is type hinted (at least with a return type)

Rexports ["abort", "status", "my_fancy_function", "my_other_funny_function"]</exports>

Beamline action - For procedures that are frequently used and involves more than a simple command

Configured as the beamline_actions of the Beamline hardware object

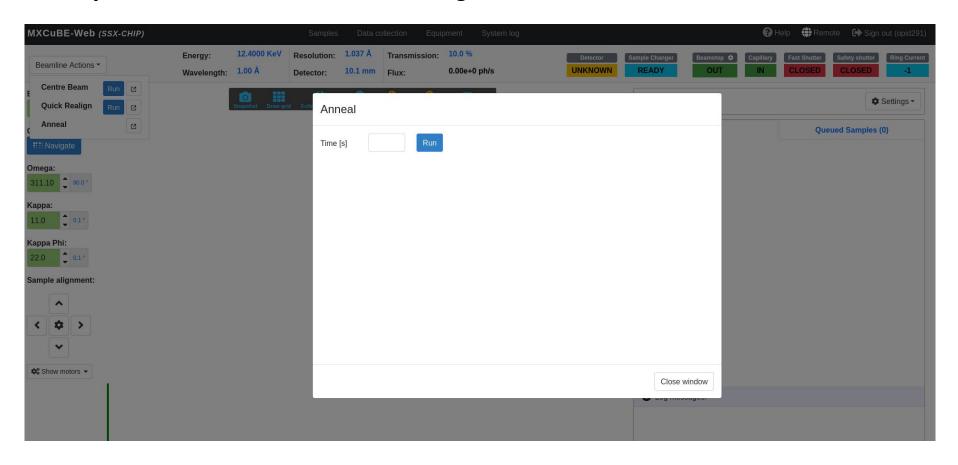


The controller commands define the command arguments programmatically via the CommandObject.add_argument method

The annotated command uses the method typehints and Pydantic models to define the arguments

Beamline actions

Example beamline action - anneal dialog



Queue entry / task - For collecting data

Write a task that takes a PyDantic model and add it to available_methods of Beamline object

```
legacy_parameters: LegacyParameters

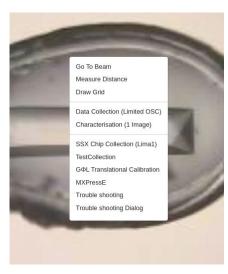
class SsxChipCollectionQueueEntry(BaseQueueEntry):

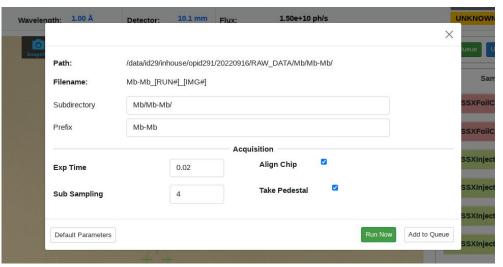
pefines the behaviour of a data collection.

pussed by the service of a data collection.

pussed by the service
```

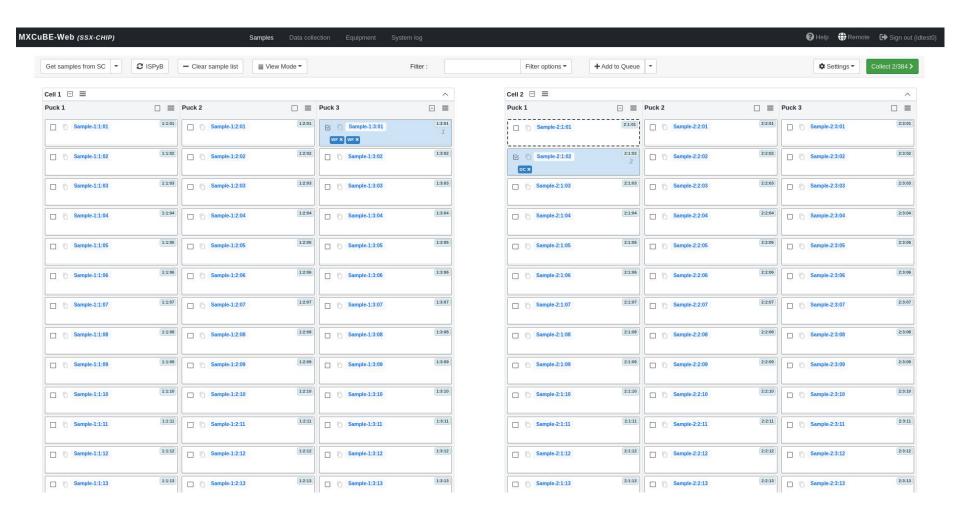
Model parsed JSONSchema generated and a dialog can be created



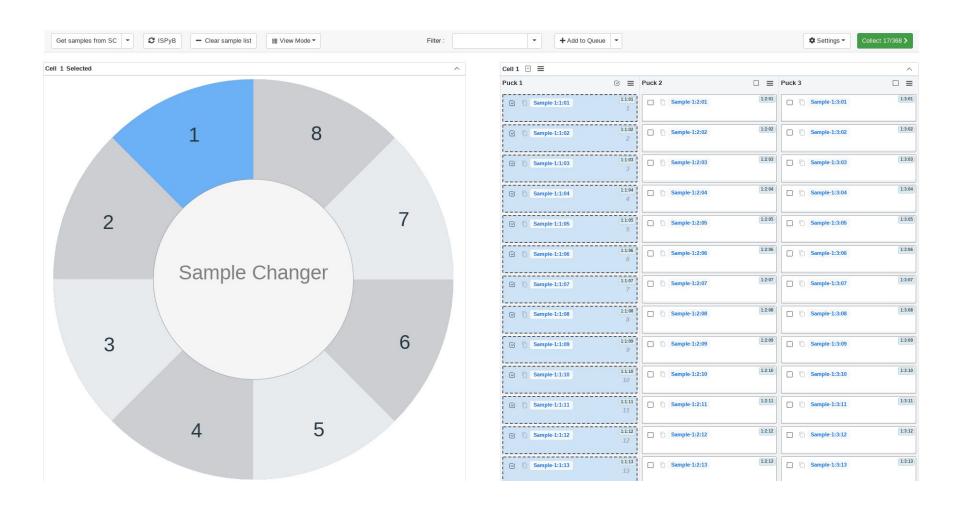




New sample list



New sample list







MXCUBE at ESRF

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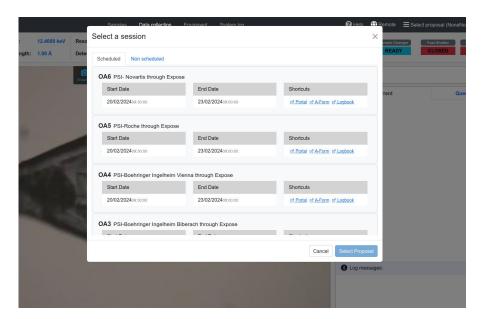
 ID23-1. ID23-2, ID30B and ID29 on mxcubeweb-4.72.0+esrf.0516 and mxcubecore-1.104.0+esrf.0516 (ID30A1 and ID30A3 are being updated)

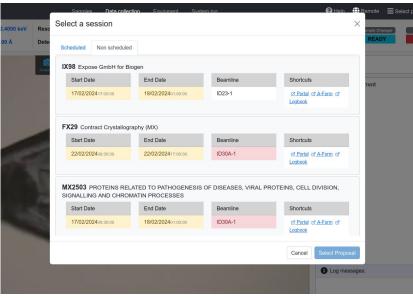
 We try to rebase on upstream and deploy roughly every two weeks - this would be helped by better test coverage :)

SSO with two factor authentication

ICAT integration ongoing

Single sign on with new proposal selection interface





Currently being validated - to be deployed within shortly

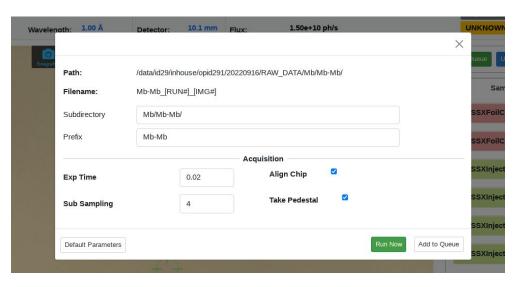
Thanks Alejandro!





MXCUBE at ESRF

- Automation features developed on MASSIF1 now available everywhere
- Automation speed up we are now up to 16 samples per hour (depending on workflow)
- Continued SSX development
 - Chip
 - Foil
 - Injector
 - Laser triggered





Future perspectives

- Continue SSX development
- Continue development on new queue functionality
- Continue development of automation
- Continue ICAT integration
- Continue work on AbstractProcessing been on hold for sometime
- Migrating from XML to YAML
- Deploy video stream solution for hutch videos
- Move to TypeScript ?
- Increase testing both backend and e2e
- Cleanup REST API and possibly exchange spectree for FlaskOpenAPI3 ?

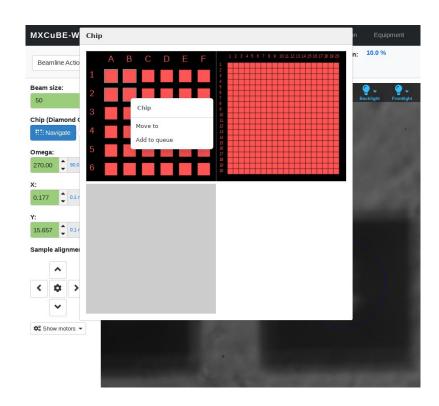


Thank you for your attention



MXCUBE at ESRF





New Queue Proposal

Example - New style queue entry

```
ssx_chip_collection.py 9+, M x
PyISPyBClient.py U
                                                                                                                      ⊳ ~ 11 Ш ...
MXCUBECORE
                              [뉴 단 강 회 HardwareObjects > queue_entry > 🏚 ssx_chip_collection.py > 😭 SsxChipCollectionQueueEntry > 🛠 execute
                                                                                                                                        HardwareObjects > queue entry > @ ssx chip collection.py > ...
 __init__.py
                                                  from pydantic import BaseModel, Field
 advanced connector.py
                                                  from devtools import debug
                                                                                                                                                  path parameters: PathParameters
 base queue entry.py
                                                                                                                                                  common parameters: CommonCollectionParamters
 characterisation.py
                                                  from mxcubecore import HardwareRepository as HWR
                                                                                                                                                  collection parameters: SSXCollectionParameters
 data_collection.py
                                                                                                                                                  user collection parameters: SSXUserCollectionParameters
                                                  from mxcubecore.HardwareObjects.queue entry.base queue entry import (
 energy_scan.py
                                                                                                                                                  legacy parameters: LegacyParameters
                                                      BaseQueueEntry,
 generic_workflow.py
 import helper.py
                                                                                                                                              class SsxChipCollectionQueueEntry(BaseQueueEntry):
 optical centring.py
                                                  from mxcubecore.HardwareObjects.queue model objects import (
 sample centring.py
                                                                                                                                                  Defines the behaviour of a data collection.
 ssx_chip_collection.py
 test collection.py
                                                                                                                                                  DATA MODEL = SsxChipColletionTaskParameters
 xray_centering.py
                                                                                                                                                  NAME = "SSXChipCollection"
                                                   credits = ["MXCuBE collaboration"]
                                                                                                                                                  REQUIRES = ["point", "line", "no shape", "chip", "mesh"]
 xray_centering2.py
 xrf spectrum.py
                                                   category = "General"
                                                                                                                                                  # New style queue entry does not take view argument.
 > SOLEIL
init .py
                                                                                                                                                  def init (self, data: SsxChipColletionTaskParameters, view=None
                                                 class SSXCollectionParameters(BaseModel):
Attenuators.py
                                                                                                                                                      super(). init (view=view, data model=TaskNode(data))
                                                      first image: int
autoprocessing.py
                                                      kappa: float
BeamInfo.py
                                                                                                                                                  def execute(self):
Beamline.py
                                                                                                                                                      super().execute()
BeamlineActions.py
BeamlineTools.py
                                                      beam size: float
                                                                                                                                                      debug(self. data model. task data)
                                                      shutterless: bool
Bliss.py
                                                      selection: list = Field([])
BlissActuator.py
                                                                                                                                                      selected regions = self. data model. task data.collection para
BlissEnergy.py
                                                                                                                                                      selected regions = selected regions if selected regions else [
BlissHutchTrigger.py
BlissMotor.py
                                                                                                                                                      for region in selected regions:
BlissMotorWPositions.py
                                                  class SSXUserCollectionParameters(BaseModel):
                                                                                                                                                          data root path = os.path.join(
                                                      sub sampling: float = Field(2, gt=0, lt=100)
BlissNState.py
                                                                                                                                                              HWR.beamline.session.get base image directory(),
                                                      take pedestal: bool = Field(True)
BlissRontecMCA.py
                                                                                                                                                              self. data model. task data.path parameters.subdir
BlissShutter.py
Camera.pv
                                                                                                                                                          process path = os.path.join(
Cats90.py
                                                                                                                                                              HWR.beamline.session.get base process directory(),
CatsBessy.py
                                                                                                                                                              self. data model. task data.path parameters.subdir
CatsMaint.py
                                                      skip existing images: bool
OUTLINE
                                                      take snapshots: int
                                                                                                                                                           fname prefix = self. data model. task data.path parameters
```

Example UI

